Vision

Release 0.1

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In this page you can find documentation on how to the Vision supercomputer, including information on how to submit and manage jobs in the best possible way.

CHAPTER

ONE

CONTENTS

1.1 About Vision

The Vision supercomputer is made by 2 compute nodes and a management node. Each compute node is a NVIDIA DGX A100 systems with the following specifications:

- CPU: Dual AMD Rome 7742, 128 cores total
- System Memory: 1TB
- GPUs: 8x NVIDIA A100 Tensor Core GPUs (40GB per GPU)
- GPU Memory: 320GB total

The two DGX A100 systems are interconneted by 8 x 200Gb/s HDR InfiniBand links.

1.1.1 Storage

The users have access to two main storage areas in Vision:

- Home folder
- External storage

Home folder

The home folder is located in /home/<username> and is shared between all nodes of the cluster (management node and compute nodes).

This folder should be used to store personal files and source code for the applications of the user.

Warning: There are no backups of the files found in the home folders.

External storage

The Vision supercomputer has an external storage for data with the capacity of 15TB. This storage is made available in the management node and in the compute nodes via an NFS share mounted in /data. Each user has a folder in /data/<username> and/or /data/projects/<username>. The home folders and the data stored in /data is shared between all nodes.

This folder should be used to store data that will be processed by your applications. The data created by your applications should also be stored in this storage area.

Warning: This storage uses a RAID 0 volume to increase read performance while feeding data to the GPUs, wihtout any redundancy. If any of the drives fail, all data in the external storage will be lost. There are no backups of this volume.

1.2 How to access Vision

To access Vision, users should use SSH connect to the frontend frontend(management node) of the Vision, which allows them to access their data, submit jobs and check job status.

To access Vision via SSH, you should use the following settings:

- hostname: main.vision.uevora.pt
- port: 22
- · username: provided by the user
- · password: provided by Vision administrators

1.2.1 Example

```
$: ssh user@main.vision.uevora.pt
[user@frontend ~]$
```

Note: Please note that users can only access Vision from the computer with the IP address provided by the user.

1.3 Quick start

In this page you can find a quick start guide on how to use Vision:

1.3.1 1. Access Vision

First you need to access Vision. To do so, you should use ssh with your credentials:

```
$: ssh user@main.vision.uevora.pt
[user@frontend ~]$
```

You can find more information on how to access Vision in How to access Vision.

1.3.2 2. Prepare your software environment

After logging in to Vision, you should change your working directory to your project directory and prepare the environment to run/build your application. You can use:

- Python Environments
- Conda
- Software modules

1.3.3 3. Create your slurm job script

After setting up your runtime environment, you should create a slurm job script, so that you can submit your job. The following is a Slurm job script to submit a project that uses Conda for dependency management:

```
#!/bin/bash
                                           # create a short name for your job
#SBATCH --job-name=cnn
#SBATCH --output="slurm-cnn-conda-%j.out" # %j will be replaced by the slurm jobID
#SBATCH --nodes=1
                                           # node count
#SBATCH --ntasks=1
                                           # total number of tasks across all nodes
#SBATCH --cpus-per-task=4
                                           # cpu-cores per task (>1 if multi-threaded_
\rightarrowtasks)
#SBATCH --gres=gpu:2
                                           # number of gpus per node
source /opt/conda/bin/activate
conda activate tf-gpu
python3 cnn.py
conda deactivate
```

The script is made of two parts: 1) specification of the resources needed as well to run the job as some general job information; and 2) specification of the taks that will be run.

In the first part of the script, we define the job name, the output file and the requested resources (4 CPUs and 2 GPUs). Then, in the second part, we define the tasks of the job. When using Conda, we should run the following:

- 1. Activate the Conda environment;
- 2. Excecute the code;
- 3. Deactivate Conda environment;

You can find more information and examples on how to submit jobs in Job examples.

1.3.4 4. Submit the job

To submit the job, you should run the following command:

```
$ sbatch script_conda.sh
Submitted batch job 144
```

You can check the job status using the following command:

\$ squeue						
	JOBID	PARTITION	NAME	USER ST	TIME	NODES NODELIST(REASON)
	143	batch	cnn	user R	0:33	1 vision2

1.4 Job management

Jobs in Vision are managed by the Slurm Workload Manager, a job scheduler which schedules jobs according to the available computational resources and the requirements of each job.

1.4.1 How to submit a jobs

To submit a job in Slurm you have to first create a job script, which defines the job, the required resources by your job and the tasks that will run in the nodes. In particular, you should:

- 1. Access Vision: check How to access Vision for details
- 2. Copy your code to Vision: use scp or another tool that transfer files over SSH.
- 3. Create a Slurm job script: check Slurm job scripts. and Job examples for details.
- 4. Submit the job: see bellow.

1.4.2 Slurm job scripts

Slurm job scripts allow users to define the jobs that will run in the cluster. These are bash scripts which allows specify: 1) general properties of job, such as name an output files; 2) the resources that will be allocated to job; and 3) the code that will be run.

The following example represents a simple Slurm job script:

```
#!/bin/bash
1
   #SBATCH --job-name=cnn
                                                # create a short name for your job
2
   #SBATCH --output="slurm-cnn-venv-%j.out" # %j will be replaced by the slurm jobID
3
   #SBATCH --nodes=1
                                                # node count
4
   #SBATCH --ntasks=1
                                                # total number of tasks across all nodes
5
                                                # cpu-cores per task (>1 if multi-threaded_
   #SBATCH --cpus-per-task=4
6
   \rightarrow tasks)
   #SBATCH --gres=gpu:2
                                                # number of gpus per node
7
8
   source venv/bin/activate
9
10
   python3 cnn.py
11
12
   deactivate
13
```

In this script, we start by 1) defining the job name and the output file (lines 3-3); 2) specifying the required resources (4 CPUs and 2 GPUs) (lines 4-7); and 3) defining the code that will run (lines 9-13). For more information about this and other examples, please check *Job examples*.

1.4.3 Accounting

The resources used by a user are allways associated with project and are logged in order to control the cluster usage. To check the resources used in a time interval, the users should use the **sreport** command:

```
$ sreport cluster AccountUtilizationByUser account=prject start=0101 -T cpu,gres/gpu
_____
Cluster/Account/User Utilization 2022-01-01T00:00:00 - 2022-05-10T23:59:59 (11232000_
\rightarrowsecs)
Usage reported in TRES Minutes
_____
 Cluster
            Account Login Proper Name
                                       TRES Name
                                                  Used
_____ ____
    hpc
           project-x
                                            cpu
                                                2863935
    hpc
          project-x
                                         gres/gpu
                                                88738
    hpc
          project-x user1
                                user1
                                            cpu
                                                    17
    hpc
           project-x
                    user1
                                user1
                                         gres/gpu
                                                    14
    hpc
           project-x
                     user2
                                user2
                                            cpu
                                                2863917
    hpc
           project-x
                     user2
                                user2
                                                  88724
                                         gres/gpu
```

In this example, the user is checking the resources consumed in the context of project project-x since January 1. Usage values are presented in minutes.

1.4.4 Common Slurm commands

In this section you can find some common useful commands to submit, manage and monitor jobs. You can find more detailed information on https://slurm.schedmd.com/quickstart.html.

Submit a job

To submit a job, you should use the sbatch command:

```
$: sbatch my-job-script.sh
Submitted batch job 439
```

In this example, the job was submitted with the id 439.

Cancel a job

To cancel a job, the user should use the scancel command:

```
$: sbatch my-job-script.sh
Submitted batch job 439
```

In this example, the job was submited with the id 439.

List job queue

To list the job queue, the user use should use the command squeue. This command lists all submited jobs to the cluster, including the job status and the node(s) where they are running:

<pre>\$: squeue</pre>								
	JOBID	PARTITION	NAME	USER	ST	TIME	NODES	NODELIST(REASON)
	444	compute	theJobNa	user	R	11:01	1	vision2

List job information

To list detailed information about a job, the user should use the scontrol command. This list the relevant information about the job, including the requested resources, the job script and the output files. The user needs to know the job id:

```
$: scontrol show jobid <jobId>
JobId=444 JobName=The_Job_Name
  UserId=user(1000) GroupId=emedeiros(1000) MCS_label=N/A
  Priority=4294901696 Nice=0 Account=asr-pt QOS=normal
   JobState=RUNNING Reason=None Dependency=(null)
   Requeue=1 Restarts=0 BatchFlag=1 Reboot=0 ExitCode=0:0
   RunTime=00:18:08 TimeLimit=5-00:00:00 TimeMin=N/A
   SubmitTime=2022-05-11T10:32:29 EligibleTime=2022-05-11T10:32:29
   AccrueTime=2022-05-11T10:32:29
   StartTime=2022-05-11T10:32:30 EndTime=2022-05-16T10:32:30 Deadline=N/A
   SuspendTime=None SecsPreSuspend=0 LastSchedEval=2022-05-11T10:32:30
   Partition=compute AllocNode:Sid=vision1:3110592
   ReqNodeList=vision2 ExcNodeList=(null)
   NodeList=vision2
   BatchHost=vision2
  NumNodes=1 NumCPUs=255 NumTasks=1 CPUs/Task=255 ReqB:S:C:T=0:0:*:*
  TRES=cpu=255,mem=980288M,node=1,billing=255,gres/gpu=8
   Socks/Node=* NtasksPerN:B:S:C=0:0:*:* CoreSpec=*
   MinCPUsNode=255 MinMemoryNode=980288M MinTmpDiskNode=0
   Features=(null) DelayBoot=00:00:00
   OverSubscribe=OK Contiguous=0 Licenses=(null) Network=(null)
   Command=/path/to/my-job-script.sh
   WorkDir=/path/of/my-job
   StdErr=/path/to/my-job-script.out
   StdIn=/dev/null
   StdOut=/path/to/my-job-script.out
  Power=
  TresPerNode=gpu:8
   NtasksPerTRES:0
```

Check node status

\$ sinfo				
PARTITION	AVAIL	TIMELIMIT	NODES	STATE NODELIST
compute*	up	infinite	1	mix vision1
compute*	up	infinite	1	alloc vision2
debug	up	15:00	1	mix vision1
debug	up	15:00	1	alloc vision2

To check the status of eacch node of the cluster, users should use the sinfo command:

1.5 Job examples

In this page you can find Slurm job script examples to submit jobs in Vision. Typically, AI applications use Conda or Python Environments to manage dependencies. The examples presented in this page are grouped by the dependency management system.

The source code of this examples can be found at: https://github.com/vistalab-uevora/vision-examples.

1.5.1 Examples:

Conda

In this page you can find Slurm job script examples that use Conda to manage the dependencies.

The source code of the exemples presented in this page can be found at: https://github.com/vistalab-uevora/ vision-examples/tree/master/examples/conda.

Convolutional Neural Network (CNN)

This is an example on how to submit a Slurm job which uses Conda for dependency management. This example uses TensorFlow and is based on the official examples from TensorFlow: https://www.tensorflow.org/tutorials/images/cnn.

Conda is available in all nodes of Vision (head and compute nodes) in /opt/conda/. You can use this Conda version, or if you prefer, can install another version in your home folder: https://docs.conda.io/projects/conda/en/latest/user-guide/ install/linux.html.

In this example we use Conda installed in /opt/conda/.

To submit a Python application that uses Conda for dependency management and project isolation as a Slurm job, you need to perform the following tasks:

- 1. Create the Conda environment with the project dependencies
- 2. Define the Slurm job script
- 3. Submit the Slurm job

1. Creating the Conda environment

To submit this script in Slurm using Conda for dependency management you should start by activating Conda:

\$ source /opt/conda/etc/profile.d/conda.sh

and then create the Conda environment. To create the Conda environment, you can use:

- create it manually
- use an environment file

Creating the Conda environment manually

To create the Conda environment manually, you should start by creating the Conda environment:

```
(base) $ conda create -n tf-gpu tensorflow-gpu
```

activate the Conda environment:

(base) \$ conda activate tf-gpu

and install the project dependencies:

```
(tf-gpu) $ pip install tensorflow==2.7.0
(tf-gpu) $ pip install matplotlib
```

After installing all dependencies, you should deactivate the virtual environment:

(tf-gpu) \$ conda deactivate

Creating the Conda environment using an environment file:

To create the Conda environment from the environment file you should run the following command:

(base) \$ conda env create -f environment.yml

This will create a Conda environment with the name and dependencies defined in the file environment.yml

2. Configure the Slurm job script

To submit the job, you first have to create a slurm batch script where you have to specify the required resources that will be allocated to your job and specify the tasks that will be run.

The following is a Slurm job script to run this project:

```
#!/bin/bash
#SBATCH --job-name=cnn  # create a short name for your job
#SBATCH --output="slurm-cnn-conda-%j.out"  # %j will be replaced by the slurm jobID
#SBATCH --nodes=1  # node count
#SBATCH --ntasks=1  # total number of tasks across all nodes
#SBATCH --cpus-per-task=4  # cpu-cores per task (>1 if multi-threaded tasks)
```

<pre>#SBATCHgres=gpu:2</pre>	# number of gpus per node
source /opt/conda/bin/activate conda activate tf-gpu	
python3 cnn.py	
conda deactivate	

The script is made of two parts: 1) specification of the resources needed as well to run the job as some general job information; and 2) specification of the taks that will be run.

In the first part of the script, we define the job name, the output file and the requested resources (4 CPUs and 2 GPUs). Then, in the second part, we define the tasks of the job. When using Conda, we should run the following:

- 1. Activate the Conda environment;
- 2. Excecute the code;
- 3. Deactivate Conda environment;

3. Submit the job

To submit the job, you should run the following command:

```
$ sbatch script_conda.sh
Submitted batch job 144
```

You can check the job status using the following command:

\$ squeue								
	JOBID PA	RTITION	NAME	USER	ST	TIME	NODES	NODELIST(REASON)
	143	batch	cnn	user	R	0:33	1	vision2

Python Environments

In this page you can find Slurm job script examples that uses Python Environment to manage the dependencies.

The source code of the exemples presented in this page can be found at: https://github.com/vistalab-uevora/vision-examples/tree/master/examples/venv.

Convolutional Neural Network (CNN)

This is an example on how to submit a Slurm job which uses Python Virtual Environment for dependency management. This example uses TensorFlow and is based in one of the official examples from TensorFlow: https://www.tensorflow.org/tutorials/images/cnn.

To submit a Python application that uses Python's Virtual Environments for dependency management and project isolation as a Slurm job, you need to perform the following tasks:

- 1. Create the Python Virtual Environment with the project dependencies
- 2. Define the Slurm job script

3. Submit the Slurm job

1. Creating the Python Virtual Environment

To submit this project in slurm using python virtualenv, you should start by creating the virtual env:

\$ python3 -m venv ./venv

After creating the virtual env, you should activate it:

```
$ source ./venv/bin/activate
```

upgrade pip:

```
(venv) $ pip install --upgrade pip
```

Install dependencies

You can install the project dependencies manually or using a requirements file.

Install dependencies manually

To install the dependencies manually, you should run:

```
(venv) $ pip install tensorflow==2.7.0
(venv) $ pip install matplotlib
```

Install dependencies using a dependency file

To install the dependencies using a requirements file, you should run:

```
(venv) $ pip install -r requirements.txt
```

After installing all dependencies, you should deactivate the virtual environment:

(venv) \$ deactivate

2. Configure the Slurm job script

To submit the job, you first have to create a slurm batch script where you have to specify the required resources that will be allocated to your job and specify the tasks that will be run.

The following is a Slurm job script to run this project:

```
#! /bin/bash
#SBATCH --job-name=cnn # create a short name for your job
#SBATCH --output="slurm-cnn-venv-%j.out" # %j will be replaced by the slurm jobID
#SBATCH --nodes=1 # node count
#SBATCH --ntasks=1 # total number of tasks across all nodes
```

```
#SBATCH --cpus-per-task=4  # cpu-cores per task (>1 if multi-threaded_

→tasks)
#SBATCH --gres=gpu:2  # number of gpus per node
source venv/bin/activate
python3 cnn.py
deactivate
```

The script is made of two parts: 1) specification of the resources needed as well to run the job as some general job information; and 2) specification of the taks that will be run.

In the first part of the script, we define the job name, the output file and the requested resources (4 CPUs and 2 GPUs). Then, in the second part, we define the tasks of the job. When using Python Virtual Environments, we should run the following steps:

- 1. Activate the Python environment;
- 2. Excecute the code;
- 3. Deactivate the Python environment;

3. Submit the job

To submit the job, you should run the following command:

```
$ sbatch script.sh
Submitted batch job 143
```

You can check the job status using the following command:

<pre>\$ squeue</pre>							
	JOBID PA	ARTITION	NAME	USER ST	TIME	NODES NODELIST(REASON)	
	143	batch	cnn	user R	0:33	1 vision2	

1.6 Software

Vision has available Python Environments and Anaconda, allowing users to create their own execution environment according to the needs of each application. Vision also has available software modules, that users can load to meet the dependencies of their applications.

1.6.1 Python Environments

To create a Pytohn Environment, the user can run the following command:

\$ python3 -m venv ./venv

After creating the environment, the user can run the following command to activate the environment and install new packages:

```
$ source ./venv/bin/activate
(venv) $ pip install tensorflow==2.7.0
(venv) $ pip install matplotlib
```

1.6.2 Anaconda

Anaconda is available at /opt/conda/. To activate Anaconda, the user should run the following command:

\$ source /opt/conda/etc/profile.d/conda.sh

To create a Conda environment, the use can run the following command:

(base) \$ conda create -n tf-gpu tensorflow-gpu

In this example, we are creating environment named tf-gpu is created, based on the Conda environment tensorflow. After creating the environment, you can activate it and install new packages:

```
(base) $ conda activate tf-gpu
(tf-gpu) $ pip install tensorflow==2.7.0
(tf-gpu) $ pip install matplotlib
```

1.6.3 Software modules

To list the available software modules, the user should run the following command:

\$ module av

To load a software module, the user should run, for example, the following command:

\$ module load foss/2021a

You can learn more about software modules in Software modules.

1.7 Software modules

One of the available options to manage software dependencies in Vision is through the use of software modules, which sets the paths for the necessary binaries, libraries, manuals and include files for the software needed by each application.

The management of these software modules in Vision is achived with the help of EasyBuild together with Lmod to load the modules. You can learn more about EasyBuild and Lmod in https://easybuild.io/ and https://lmod.readthedocs.io/.

You can learn more abot using software modules in *Using modules*. The list of the software modules available in Vision can be found in *Available software modules*.

1.7.1 Using modules

To use software modules, the user just need to use the module load or module add commands to load the required module. When a module is loaded, all required dependencies will also be loaded, making the software ready for the user.

Vision uses a hierarchical module naming scheme (hmns) in which modules availability follows the software hierarchy Core/Compiler/MPI. Core refers to the basic core modules that have to be loaded in order to have access to next levels of software compiled against a specific compiler and a MPI API.

After logging into Vision, the user should execute the command module av (av for available) to list the available core modules:

```
$ module av
  ------/opt/software/modules/all/Core -------
                            binutils/2.36.1
  Anaconda3/2021.05
                                                      (D)
  Bison/3.8.2
                            cuDNN/8.2.1.32-CUDA-11.3.1
  CUDA/11.3.1
                            flex/2.6.4
                            foss/2021a
  GCC/10.3.0
  GCCcore/10.2.0
                            gettext/0.21
  GCCcore/10.3.0
                    (D)
                            gompi/2021a
  Java/11.0.2
                    (11)
                            ncurses/6.2
  M4/1.4.19
                            pkg-config/0.29.2
  OpenSSL/1.1
                            zlib/1.2.11
  binutils/2.35
 Where:
  Aliases: Aliases exist: foo/1.2.3 (1.2) means that "module load foo/1.2" will load.
\rightarrow foo/1.2.3
  D:
            Default Module
```

In the available modules, you can find the toolchains foss/2021a and gompi/2021a, which you can load to access other modules which are built againts each toolchain, e.g.: module load foss/2021a. After loading the toolchain, you can view the associated modules using running again the comman module av:

```
$ module load foss/2021a
$ module av
------/opt/software/modules/all/MPI/GCC/10.3.0/OpenMPI/4.1.1 -------
  FFTW/3.3.9
                           (L)
                                 h5py/3.2.1
  HDF5/1.10.7
                                 magma/2.6.1-CUDA-11.3.1
  ScaLAPACK/2.1.0-fb
                           (L)
                                 matplotlib/3.4.2
  SciPy-bundle/2021.05
                                 scikit-learn/0.24.2
  TensorFlow/2.5.3-CUDA-11.3.1
                                 tensorboard/2.8.0
  TensorFlow/2.6.0-CUDA-11.3.1 (D)
  ------ /opt/software/modules/all/Compiler/GCC/10.3.0 -------
  FlexiBLAS/3.0.4 (L)
                     OpenBLAS/0.3.15 (L)
                                         OpenMPI/4.1.1 (L)
Autoconf/2.71
                                  cppy/1.1.0
  Automake/1.16.3
                                  double-conversion/3.1.5
  Autotools/20210128
                                  expat/2.2.9
  Bazel/3.7.2
                                  expecttest/0.1.3
```

Bison/3.7.6			flatbuffers-pvthon/2.0	
Brotli/1.0.9			flatbuffers/2.0.0	
CMake/3.20.1			flex/2.6.4	(D)
DB/18.1.40			font config/2.13.93	
Eigen/3.3.9			freetype/2.10.4	
FFmpeq/4, 3, 2			aettext/0.21	(D)
FriBidi/1.0.10			giflib/5.2.1	
GDRCopy/2.2			ait/2.32.0-nodocs	
$GMP/6_2 \cdot 1$			$qperf/3_1$	
TCII/69_1			groff/1.22.4	
JsonCpp/1.9.4			g_ip/1.10	
LAME/3.100			help2man/1.48.3	
LMDB/0.9.28			hwloc/2.4.1	(L)
LibTIFF/4.2.0			hypothesis/6.13.1	
M4/1.4.18			intltool/0.51.0	
MPFR/4.1.0			ibiakit/2.1	
Meson/ $0.58.0$			libarchive/3.5.1	
NASM/2.15.05			libevent/2.1.12	(L)
NCCL/2.10.3-CUDA-1	1.3.1		libfabric/1.12.1	(L)
Ninia/1.10.2			libffi/3.3	
PCRE/8.44			libipeg-turbo/2.0.6	
PMIx/3.2.3		(L)	libpciaccess/0.16	(L)
Perl/5.32.1-minima	l		libpng/1.6.37	
Perl/5.32.1		(D)	libreadline/8.1	
Pillow/8.2.0			libtool/2.4.6	
PyYAML/5.4.1			libxml2/2.9.10	(L)
Python/2.7.18-bare	<u>1</u>		libyaml/0.2.5	
Python/3.9.5-bare			lz4/1.9.3	
Python/3.9.5		(D)	makeinfo/6.7-minimal	
Qhull/2020.2			ncurses/6.2	(D)
Rust/1.52.1			nsync/1.24.0	
SQLite/3.35.4			numactl/2.0.14	(L)
Szip/2.1.1			pkg-config/0.29.2	(D)
Tcl/8.6.11			pkgconfig/1.5.4-python	
Tk/8.6.11			protobuf-python/3.17.3	
Tkinter/3.9.5			protobuf/3.17.3	
UCX-CUDA/1.10.0-CU	JDA-11.3.1		pybind11/2.6.2	
UCX/1.10.0		(L)	snappy/1.1.8	
UnZip/6.0			<pre>typing-extensions/3.10.0.0</pre>	
X11/20210518			util-linux/2.36	
XZ/5.2.5		(L)	x264/20210414	
Yasm/1.3.0			x265/3.5	
Zip/3.0			xorg-macros/1.19.3	
binutils/2.36.1		(L,D)	zlib/1.2.11	(L,D)
bzip2/1.0.8			zstd/1.4.9	
cURL/7.76.0				
		_		
 An a serie la 2 /2024 - 25	/opt/s	oftware/mo	odules/all/Core	
Anaconda3/2021.05		pinutils/2	4.30.1	
BISON/3.8.2	(ח)	$CUDNN/\delta.2$.1.34-CUDA-11.3.1	
CUDA/11.3.1	(\mathbf{I})	ILEX/2.0.4	±	
GCC/10.3.0	(L)	1055/20218	4 (L)	

GCCcore/1	0.2.0		gettext/0.21					
GCCcore/1	0.3.0	(L,D)	gompi/2021a					
Java/11.0	.2	(11)	ncurses/6.2					
M4/1.4.19		(D)	pkg-config/0.29.2					
0penSSL/1	.1	(L)	zlib/1.2.11					
binutils/	2.35							
Where:								
L:	Module i	s loaded						
Aliases:	Aliases	exist: f	oo/1.2.3 (1.2) means that "module load foo/1.2" will load					
⊶foo/1.2.3								
D:	Default	Module						

After loading the desired toolchain, the user can load the desired moduled using the module load command. For example, to load TensorFlow, the user can run the following command:

\$ module load TensorFlow

To list the modules that are loaded, the user should use the module list command:

```
$ module list
Currently Loaded Modules:
  1) GCCcore/10.3.0
                                  29) Tcl/8.6.11
  2) zlib/1.2.11
                                  30) SQLite/3.35.4
  3) binutils/2.36.1
                                  31) GMP/6.2.1
                                  32) libffi/3.3
  4) GCC/10.3.0
  5) numact1/2.0.14
                                  33) Python/3.9.5
  6) XZ/5.2.5
                                  34) pybind11/2.6.2
  7) libxml2/2.9.10
                                  35) SciPy-bundle/2021.05
  8) libpciaccess/0.16
                                  36) Szip/2.1.1
  9) hwloc/2.4.1
                                  37) HDF5/1.10.7
 10) OpenSSL/1.1
                                  38) h5py/3.2.1
 11) libevent/2.1.12
                                  39) cURL/7.76.0
12) UCX/1.10.0
                                  40) double-conversion/3.1.5
13) libfabric/1.12.1
                                  41) flatbuffers/2.0.0
14) PMIx/3.2.3
                                  42) giflib/5.2.1
15) OpenMPI/4.1.1
                                  43) ICU/69.1
16) OpenBLAS/0.3.15
                                  44) JsonCpp/1.9.4
17) FlexiBLAS/3.0.4
                                  45) NASM/2.15.05
18) FFTW/3.3.9
                                  46) libjpeg-turbo/2.0.6
19) ScaLAPACK/2.1.0-fb
                                  47) LMDB/0.9.28
20) foss/2021a
                                  48) nsync/1.24.0
21) CUDA/11.3.1
                                  49) protobuf/3.17.3
22) cuDNN/8.2.1.32-CUDA-11.3.1
                                  50) protobuf-python/3.17.3
23) GDRCopy/2.2
                                  51) flatbuffers-python/2.0
24) UCX-CUDA/1.10.0-CUDA-11.3.1 52) typing-extensions/3.10.0.0
25) NCCL/2.10.3-CUDA-11.3.1
                                  53) libpng/1.6.37
26) bzip2/1.0.8
                                  54) snappy/1.1.8
                                  55) TensorFlow/2.6.0-CUDA-11.3.1
27) ncurses/6.2
28) libreadline/8.1
```

If the user wants to "unload" the loaded modules, he can use the command module purge:

```
$ module purge
$ module list
No modules loaded
```

1.7.2 Available software modules

In this page you can find the list of the available software modules in Vision and instructions on how to load them.

Loading software modules

To load any of the modules found in the following list, you should first run the command module spider to list the modules that you should before loading the desired module.

For example, to load the Gromacs module, the user should first run:

```
$ module spider GROMACS
....
You will need to load all module(s) on any one of the lines below before the
→"GROMACS/2021.3-CUDA-11.3.1" module is available to load.
GCC/10.3.0 OpenMPI/4.1.1
....
```

Then, the user can load all the needed software modules:

```
$ module load GCC/10.3.0 OpenMPI/4.1.1 GROMACS
```

List of software modules

The following is a list of software modules available in Vision. You can check this list in Vision by running the command module spider:

```
The following is a list of the modules and extensions currently available:

Anaconda3: Anaconda3/2021.05

Built to complement the rich, open source Python community, the Anaconda platform.

provides an enterprise-ready data analytics platform that empowers companies to adopt.

a modern open

data science analytics architecture.

Autoconf: Autoconf/2.69, Autoconf/2.71

Autoconf is an extensible package of M4 macros that produce shell scripts to.

automatically configure software source code packages. These scripts can adapt the.

packages to many
```

kinds of UNIX-like systems without manual user intervention. Autoconf creates $a_{\perp} \rightarrow configuration$ script for a package from a template file that lists the operating_ $\rightarrow system$ features that
the package can use, in the form of M4 macro calls.
<pre>Automake: Automake/1.16.1, Automake/1.16.2, Automake/1.16.3, Automake/1.16.4 Automake: GNU Standards-compliant Makefile generator</pre>
Autotools: Autotools/20180311, Autotools/20200321, Autotools/20210128, Autotools/ →20210726 This bundle collect the standard GNU build tools: Autoconf, Automake and libtool
Bazel: Bazel/3.7.2 Bazel is a build tool that builds code quickly and reliably. It is used to build the_ →majority of Google's software.
Bison: Bison/3.5.3, Bison/3.7.1, Bison/3.7.6, Bison/3.8.2 Bison is a general-purpose parser generator that converts an annotated context-free. →grammar into a deterministic LR or generalized LR (GLR) parser employing LALR(1). →parser tables.
Brotli: Brotli/1.0.9 Brotli is a generic-purpose lossless compression algorithm that compresses data. →using a combination of a modern variant of the LZ77 algorithm, Huffman coding and 2nd. →order context modeling, with a compression ratio comparable to the best currently available. →general-purpose compression methods. It is similar in speed with deflate but offers. →more dense compression. The specification of the Brotli Compressed Data Format is defined in. →RFC 7932.
CMake: CMake/3.16.4, CMake/3.18.4, CMake/3.20.1 CMake, the cross-platform, open-source build system. CMake is a family of tools_ ⊸designed to build, test and package software.
CUDA: CUDA/11.1.1, CUDA/11.3.1 CUDA (formerly Compute Unified Device Architecture) is a parallel computing platform. → and programming model created by NVIDIA and implemented by the graphics processing. → units (GPUs) that they produce. CUDA gives developers access to the virtual instruction set and. → memory of the parallel computational elements in CUDA GPUs.
CUDAcore: CUDAcore/11.1.1 CUDA (formerly Compute Unified Device Architecture) is a parallel computing platform. → and programming model created by NVIDIA and implemented by the graphics processing. → units (GPUs) that they produce. CUDA gives developers access to the virtual instruction set and. → memory of the parallel computational elements in CUDA GPUs.
Check: Check/0.15.2 Check is a unit testing framework for C. It features a simple interface for defining. unit tests, putting little in the way of the developer. Tests are run in a separate.

 \rightarrow address space, so both assertion failures and code errors that cause segmentation faults or \rightarrow other signals can be caught. Test results are reportable in the following: Subunit, \rightarrow TAP, XML, and a generic logging format. DB: DB/18.1.32, DB/18.1.40 Berkeley DB enables the development of custom data management solutions, without the ⇔overhead traditionally associated with such custom projects. Doxygen: Doxygen/1.8.17, Doxygen/1.9.1 Doxygen is a documentation system for C++, C, Java, Objective-C, Python, IDL (Corba_ \rightarrow and Microsoft flavors), Fortran, VHDL, PHP, C#, and to some extent D. Eigen: Eigen/3.3.8, Eigen/3.3.9 Eigen is a C++ template library for linear algebra: matrices, vectors, numerical. →solvers, and related algorithms. FFTW: FFTW/3.3.8, FFTW/3.3.9 FFTW is a C subroutine library for computing the discrete Fourier transform (DFT) in_ \rightarrow one or more dimensions, of arbitrary input size, and of both real and complex data. FFmpeg: FFmpeg/4.3.1, FFmpeg/4.3.2 A complete, cross-platform solution to record, convert and stream audio and video. FlexiBLAS: FlexiBLAS/3.0.4 FlexiBLAS is a wrapper library that enables the exchange of the BLAS and LAPACK -- implementation used by a program without recompiling or relinking it. FriBidi: FriBidi/1.0.10 The Free Implementation of the Unicode Bidirectional Algorithm. GCC: GCC/9.3.0, GCC/10.2.0, GCC/10.3.0 The GNU Compiler Collection includes front ends for C, C++, Objective-C, Fortran, →Java, and Ada, as well as libraries for these languages (libstdc++, libgcj,...). GCCcore: GCCcore/9.3.0, GCCcore/10.2.0, GCCcore/10.3.0, GCCcore/11.2.0 The GNU Compiler Collection includes front ends for C, C++, Objective-C, Fortran, →Java, and Ada, as well as libraries for these languages (libstdc++, libgcj,...). GDRCopy: GDRCopy/2.1-CUDA-11.1.1, GDRCopy/2.2 A low-latency GPU memory copy library based on NVIDIA GPUDirect RDMA technology. GMP: GMP/6.2.0, GMP/6.2.1 GMP is a free library for arbitrary precision arithmetic, operating on signed. ⇒integers, rational numbers, and floating point numbers. GROMACS: GROMACS/2021.3-CUDA-11.3.1 GROMACS is a versatile package to perform molecular dynamics, i.e. simulate the \rightarrow Newtonian equations of motion for systems with hundreds to millions of particles. This ⇒is a GPU enabled build, containing both MPI and threadMPI builds. It also contains the gmxapi

⁽continues on next page)

 \rightarrow extension for the single precision MPI build. HDF: HDF/4.2.15 HDF (also known as HDF4) is a library and multi-object file format for storing and →managing data between machines. HDF5: HDF5/1.10.6, HDF5/1.10.7 HDF5 is a data model, library, and file format for storing and managing data. It. \rightarrow supports an unlimited variety of datatypes, and is designed for flexible and efficient. \rightarrow I/O and for high volume and complex data. ICU: ICU/69.1 ICU is a mature, widely used set of C/C++ and Java libraries providing Unicode and →Globalization support for software applications. Java: Java/11.0.2 Java Platform, Standard Edition (Java SE) lets you develop and deploy Java. →applications on desktops and servers. JsonCpp: JsonCpp/1.9.4 JsonCpp is a C++ library that allows manipulating JSON values, including. \rightarrow serialization and deserialization to and from strings. It can also preserve existing \rightarrow comment in unserialization/serialization steps, making it a convenient format to store user \rightarrow input files. Julia: Julia/1.7.2-linux-x86_64 Julia is a high-level, high-performance dynamic programming language for numerical \hookrightarrow computing LAME: LAME/3.100 LAME is a high quality MPEG Audio Layer III (MP3) encoder licensed under the LGPL. LMDB: LMDB/0.9.28 LMDB is a fast, memory-efficient database. With memory-mapped files, it has the read. \rightarrow performance of a pure in-memory database while retaining the persistence of standard →disk-based databases. LibTIFF: LibTIFF/4.1.0, LibTIFF/4.2.0 tiff: Library and tools for reading and writing TIFF data files Lua: Lua/5.4.3 Lua is a powerful, fast, lightweight, embeddable scripting language. Lua combines \rightarrow simple procedural syntax with powerful data description constructs based on \hookrightarrow associative arrays and extensible semantics. Lua is dynamically typed, runs by interpreting bytecode for a \rightarrow register-based virtual machine, and has automatic memory management with incremental →garbage collection, making it ideal for configuration, scripting, and rapid prototyping.

M4: M4/1.4.18, M4/1.4.19 GNU M4 is an implementation of the traditional Unix macro processor. It is mostly_ \rightarrow SVR4 compatible although it has some extensions (for example, handling more than 9. \rightarrow positional parameters to macros). GNU M4 also has built-in functions for including files, →running shell commands, doing arithmetic, etc. MPFR: MPFR/4.1.0 The MPFR library is a C library for multiple-precision floating-point computations. \rightarrow with correct rounding. Meson: Meson/0.55.1-Python-3.8.2, Meson/0.55.3, Meson/0.58.0 Meson is a cross-platform build system designed to be both as fast and as user_ \rightarrow friendly as possible. NASM: NASM/2.15.05 NASM: General-purpose x86 assembler NCCL: NCCL/2.8.3-CUDA-11.1.1, NCCL/2.10.3-CUDA-11.3.1 The NVIDIA Collective Communications Library (NCCL) implements multi-GPU and multi--- node collective communication primitives that are performance optimized for NVIDIA_ \rightarrow GPUs. Ninja: Ninja/1.10.0, Ninja/1.10.1, Ninja/1.10.2 Ninja is a small build system with a focus on speed. OpenBLAS: OpenBLAS/0.3.12, OpenBLAS/0.3.15 OpenBLAS is an optimized BLAS library based on GotoBLAS2 1.13 BSD version. OpenMPI: OpenMPI/4.0.3, OpenMPI/4.0.5, OpenMPI/4.1.1 The Open MPI Project is an open source MPI-3 implementation. OpenSSL: OpenSSL/1.1 The OpenSSL Project is a collaborative effort to develop a robust, commercial-grade, --full-featured, and Open Source toolchain implementing the Secure Sockets Layer (SSL v2/ \rightarrow v3) and Transport Layer Security (TLS v1) protocols as well as a full-strength general. \rightarrow purpose cryptography library. PCRE: PCRE/8.44 The PCRE library is a set of functions that implement regular expression pattern. \hookrightarrow matching using the same syntax and semantics as Perl 5. PMIx: PMIx/3.1.5, PMIx/3.2.3 Process Management for Exascale Environments PMI Exascale (PMIx) represents an. \rightarrow attempt to provide an extended version of the PMI standard specifically designed to. →support clusters up to and including exascale sizes. The overall objective of the project is not to. \rightarrow branch the existing pseudo-standard definitions - in fact, PMIx fully supports both of \rightarrow the existing PMI-1 and PMI-2 APIs - but rather to (a) augment and extend those APIs to. \rightarrow eliminate some current restrictions that impact scalability, and (b) provide a

→reference implementation of the PMI-server that demonstrates the desired level of scalability. Perl: Perl/5.30.2-minimal, Perl/5.30.2, Perl/5.32.0-minimal, Perl/5.32.0, Perl/5.32.1-→minimal, Perl/5.32.1, Perl/5.34.0 Larry Wall's Practical Extraction and Report Language This is a minimal build. \hookrightarrow without any modules. Should only be used for build dependencies. Pillow: Pillow/8.0.1, Pillow/8.2.0 Pillow is the 'friendly PIL fork' by Alex Clark and Contributors. PIL is the Python. ⇔Imaging Library by Fredrik Lundh and Contributors. PyTorch: PyTorch/1.10.0-CUDA-11.3.1 Tensors and Dynamic neural networks in Python with strong GPU acceleration. PyTorch. \rightarrow is a deep learning framework that puts Python first. PyYAML: PyYAML/5.3.1, PyYAML/5.4.1 PyYAML is a YAML parser and emitter for the Python programming language. Python: Python/2.7.18-bare, Python/2.7.18, Python/3.8.2, Python/3.8.6, Python/3.9.5- \rightarrow bare, Python/3.9.5 Python is a programming language that lets you work more quickly and integrate your \rightarrow systems more effectively. Qhull: Qhull/2020.2 Qhull computes the convex hull, Delaunay triangulation, Voronoi diagram, halfspace --intersection about a point, furthest-site Delaunay triangulation, and furthest-site →Voronoi diagram. The source code runs in 2-d, 3-d, 4-d, and higher dimensions. Qhull \rightarrow implements the Quickhull algorithm for computing the convex hull. Rust: Rust/1.52.1 Rust is a systems programming language that runs blazingly fast, prevents segfaults, \rightarrow and guarantees thread safety. SQLite: SQLite/3.31.1, SQLite/3.33.0, SQLite/3.35.4 SQLite: SQL Database Engine in a C Library ScaLAPACK: ScaLAPACK/2.1.0-fb, ScaLAPACK/2.1.0 The ScaLAPACK (or Scalable LAPACK) library includes a subset of LAPACK routines_ →redesigned for distributed memory MIMD parallel computers. SciPy-bundle: SciPy-bundle/2020.11, SciPy-bundle/2021.05 Bundle of Python packages for scientific software Szip: Szip/2.1.1 Szip compression software, providing lossless compression of scientific data Tcl: Tcl/8.6.10, Tcl/8.6.11 Tcl (Tool Command Language) is a very powerful but easy to learn dynamic programming_ \rightarrow language, suitable for a very wide range of uses, including web and desktop \rightarrow applications,

(continued from previous page) networking, administration, testing and many more. TensorFlow: TensorFlow/2.5.3-CUDA-11.3.1, TensorFlow/2.6.0-CUDA-11.3.1 An open-source software library for Machine Intelligence Tk: Tk/8.6.11 Tk is an open source, cross-platform widget toolchain that provides a library of →basic elements for building a graphical user interface (GUI) in many different \hookrightarrow programming languages. Tkinter: Tkinter/3.9.5 Tkinter module, built with the Python buildsystem UCX: UCX/1.8.0, UCX/1.9.0-CUDA-11.1.1, UCX/1.10.0, UCX/1.11.2 Unified Communication X An open-source production grade communication framework for →data centric and high-performance applications UCX-CUDA: UCX-CUDA/1.10.0-CUDA-11.3.1 Unified Communication X An open-source production grade communication framework for \rightarrow data centric and high-performance applications This module adds the UCX CUDA support. UDUNITS: UDUNITS/2.2.26, UDUNITS/2.2.28 UDUNITS supports conversion of unit specifications between formatted and binary \rightarrow forms, arithmetic manipulation of units, and conversion of values between compatible. \rightarrow scales of measurement. UnZip: UnZip/6.0 UnZip is an extraction utility for archives compressed in .zip format (also called \rightarrow for MS-DOS and with Info-ZIP's own Zip program, our primary objectives have been portability. \rightarrow and non-MSDOS functionality. X11: X11/20200222, X11/20201008, X11/20210518 The X Window System (X11) is a windowing system for bitmap displays XZ: XZ/5.2.5 xz: XZ utilities Yasm: Yasm/1.3.0 Yasm: Complete rewrite of the NASM assembler with BSD license Zip: Zip/3.0 Zip is a compression and file packaging/archive utility. Although highly compatible. →both with PKWARE's PKZIP and PKUNZIP utilities for MS-DOS and with Info-ZIP's own →UnZip, our primary objectives have been portability and other-than-MSDOS functionality binutils: binutils/2.34, binutils/2.35, binutils/2.36.1, binutils/2.37 binutils: GNU binary utilities

bzip2: bzip2/1.0.8 bzip2 is a freely available, patent free, high-quality data compressor. It typically_ \rightarrow compresses files to within 10% to 15% of the best available techniques (the PPM family_ ⊶of statistical compressors), whilst being around twice as fast at compression and six_ \rightarrow times faster at decompression. cURL: cURL/7.69.1, cURL/7.72.0, cURL/7.76.0 libcurl is a free and easy-to-use client-side URL transfer library, supporting DICT, →FILE, FTP, FTPS, Gopher, HTTP, HTTPS, IMAP, IMAPS, LDAP, LDAPS, POP3, POP3S, RTMP, \rightarrow RTSP, SCP, SFTP, SMTP, SMTPS, Telnet and TFTP. libcurl supports SSL certificates, HTTP POST, →HTTP PUT, FTP uploading, HTTP form based upload, proxies, cookies, user+password \rightarrow authentication (Basic, Digest, NTLM, Negotiate, Kerberos), file transfer resume, http proxy \rightarrow tunneling and more. cppy: cppy/1.1.0 A small C++ header library which makes it easier to write Python extension modules. \rightarrow The primary feature is a PyObject smart pointer which automatically handles reference. ⇔counting and provides convenience methods for performing common object operations. cuDNN: cuDNN/8.0.4.30-CUDA-11.1.1, cuDNN/8.2.1.32-CUDA-11.3.1 The NVIDIA CUDA Deep Neural Network library (cuDNN) is a GPU-accelerated library of \rightarrow primitives for deep neural networks. double-conversion: double-conversion/3.1.5 Efficient binary-decimal and decimal-binary conversion routines for IEEE doubles. expat: expat/2.2.9, expat/2.4.1 Expat is an XML parser library written in C. It is a stream-oriented parser in which. \rightarrow an application registers handlers for things the parser might find in the XML document. \rightarrow (like start tags) expecttest: expecttest/0.1.3 This library implements expect tests (also known as "golden" tests). Expect tests \rightarrow are a method of writing tests where instead of hard-coding the expected output of a. →test, you run the test to get the output, and the test framework automatically populates the \rightarrow expected output. If the output of the test changes, you can rerun the test with the →environment variable EXPECTTEST_ACCEPT=1 to automatically update the expected output. flatbuffers: flatbuffers/2.0.0 FlatBuffers: Memory Efficient Serialization Library flatbuffers-python: flatbuffers-python/2.0 Python Flatbuffers runtime library.

flex: flex/2.6.4 Flex (Fast Lexical Analyzer) is a tool for generating scanners. A scanner, sometimes \rightarrow called a tokenizer, is a program which recognizes lexical patterns in text. fontconfig: fontconfig/2.13.92, fontconfig/2.13.93 Fontconfig is a library designed to provide system-wide font configuration, →customization and application access. foss: foss/2021a GNU Compiler Collection (GCC) based compiler toolchain, including OpenMPI for MPI ⇔ support, OpenBLAS (BLAS and LAPACK support), FFTW and ScaLAPACK. fosscuda: fosscuda/2020b GCC based compiler toolchain __with CUDA support__, and including OpenMPI for MPI_ freetype: freetype/2.10.1, freetype/2.10.3, freetype/2.10.4 FreeType 2 is a software font engine that is designed to be small, efficient, highly_ -customizable, and portable while capable of producing high-quality output (glyph. \rightarrow images). It can be used in graphics libraries, display servers, font conversion tools, text image \rightarrow generation tools, and many other products as well. gcccuda: gcccuda/2020b GNU Compiler Collection (GCC) based compiler toolchain, along with CUDA toolkit. gettext: gettext/0.20.1, gettext/0.21 GNU 'gettext' is an important step for the GNU Translation Project, as it is an. \rightarrow asset on which we may build many other steps. This package offers to programmers, \rightarrow translators, and even users, a well integrated set of tools and documentation giflib: giflib/5.2.1 giflib is a library for reading and writing gif images. It is API and ABI compatible. →with libungif which was in wide use while the LZW compression algorithm was patented. git: git/2.23.0-nodocs, git/2.28.0-nodocs, git/2.32.0-nodocs Git is a free and open source distributed version control system designed to handle. \rightarrow everything from small to very large projects with speed and efficiency. gompi: gompi/2020a, gompi/2021a GNU Compiler Collection (GCC) based compiler toolchain, including OpenMPI for MPI \rightarrow support. gompic: gompic/2020b GNU Compiler Collection (GCC) based compiler toolchain along with CUDA toolkit, \rightarrow including OpenMPI for MPI support with CUDA features enabled. gperf: gperf/3.1 GNU gperf is a perfect hash function generator. For a given list of strings, it \rightarrow produces a hash function and hash table, in form of C or C++ code, for looking up a \rightarrow value depending

on the input string. The hash function is perfect, which means that the hash table. →has no collisions, and the hash table lookup needs a single string comparison only. groff: groff/1.22.4 Groff (GNU troff) is a typesetting system that reads plain text mixed with. ⇔ formatting commands and produces formatted output. gzip: gzip/1.10 gzip (GNU zip) is a popular data compression program as a replacement for compress h5py: h5py/3.2.1 HDF5 for Python (h5py) is a general-purpose Python interface to the Hierarchical →Data Format library, version 5. HDF5 is a versatile, mature scientific software. \rightarrow library designed for the fast, flexible storage of enormous amounts of data. help2man: help2man/1.47.12, help2man/1.47.16, help2man/1.48.3 help2man produces simple manual pages from the '--help' and '--version' output of \rightarrow other commands. hwloc: hwloc/2.2.0, hwloc/2.4.1 The Portable Hardware Locality (hwloc) software package provides a portable \rightarrow abstraction (across OS, versions, architectures, ...) of the hierarchical topology of →modern architectures, including NUMA memory nodes, sockets, shared caches, cores and →simultaneous multithreading. It also gathers various system attributes such as cache \rightarrow and memory information as well as the locality of I/O devices such as network interfaces, \rightarrow InfiniBand HCAs or GPUs. It primarily aims at helping applications with gathering \rightarrow information about modern computing hardware so as to exploit it accordingly and efficiently. hypothesis: hypothesis/5.41.2, hypothesis/5.41.5, hypothesis/6.13.1 Hypothesis is an advanced testing library for Python. It lets you write tests which \rightarrow are parametrized by a source of examples, and then generates simple and comprehensible. \rightarrow examples that make your tests fail. This lets you find more bugs in your code with less work. iimpi: iimpi/2021a, iimpi/2021b Intel C/C++ and Fortran compilers, alongside Intel MPI. imkl: imkl/2021.2.0, imkl/2021.4.0 Intel oneAPI Math Kernel Library imkl-FFTW: imkl-FFTW/2021.4.0 FFTW interfaces using Intel oneAPI Math Kernel Library impi: impi/2021.2.0, impi/2021.4.0 Intel MPI Library, compatible with MPICH ABI intel: intel/2021a, intel/2021b Compiler toolchain including Intel compilers, Intel MPI and Intel Math Kernel

```
(continued from previous page)
```

```
→Library (MKL).
 intel-compilers: intel-compilers/2021.2.0, intel-compilers/2021.4.0
   Intel C, C++ & Fortran compilers (classic and oneAPI)
 intltool: intltool/0.51.0
   intltool is a set of tools to centralize translation of many different file formats.
→using GNU gettext-compatible PO files.
 iompi: iompi/2021a
   Intel C/C++ and Fortran compilers, alongside Open MPI.
 jbigkit: jbigkit/2.1
   JBIG-KIT is a software implementation of the JBIG1 data compression standard (ITU-T_
\rightarrowT.82), which was designed for bi-level image data, such as scanned documents.
 libarchive: libarchive/3.4.3, libarchive/3.5.1
   Multi-format archive and compression library
 libevent: libevent/2.1.11, libevent/2.1.12
   The libevent API provides a mechanism to execute a callback function when a specific
\rightarrow event occurs on a file descriptor or after a timeout has been reached. Furthermore,
→libevent
   also support callbacks due to signals or regular timeouts.
 libfabric: libfabric/1.11.0, libfabric/1.12.1
   Libfabric is a core component of OFI. It is the library that defines and exports the
-user-space API of OFI, and is typically the only software that applications deal with
\rightarrow directly.
   It works in conjunction with provider libraries, which are often integrated directly.
\rightarrowinto libfabric.
 libffi: libffi/3.3
   The libffi library provides a portable, high level programming interface to various.
\rightarrow calling conventions. This allows a programmer to call any function specified by a call
\rightarrow interface
   description at run-time.
 libiconv: libiconv/1.16
   Libiconv converts from one character encoding to another through Unicode conversion
 libjpeg-turbo: libjpeg-turbo/2.0.5, libjpeg-turbo/2.0.6
   libjpeg-turbo is a fork of the original IJG libjpeg which uses SIMD to accelerate.
\rightarrow baseline JPEG compression and decompression. libjpeg is a library that implements JPEG.
→image
   encoding, decoding and transcoding.
 libpciaccess: libpciaccess/0.16
   Generic PCI access library.
 libpng: libpng/1.6.37
   libpng is the official PNG reference library
```

libreadline: libreadline/8.0, libreadline/8.1 The GNU Readline library provides a set of functions for use by applications that. \rightarrow allow users to edit command lines as they are typed in. Both Emacs and vi editing. →modes are available. The Readline library includes additional functions to maintain a list of \rightarrow previously-entered command lines, to recall and perhaps reedit those lines, and →perform csh-like history expansion on previous commands. libtirpc: libtirpc/1.3.2 Libtirpc is a port of Suns Transport-Independent RPC library to Linux. libtool: libtool/2.4.6 GNU libtool is a generic library support script. Libtool hides the complexity of \rightarrow using shared libraries behind a consistent, portable interface. libxml2: libxml2/2.9.10 Libxml2 is the XML C parser and toolchain developed for the Gnome project (but_ →usable outside of the Gnome platform). libyaml: libyaml/0.2.5 LibYAML is a YAML parser and emitter written in C. lz4: lz4/1.9.2, lz4/1.9.3 LZ4 is lossless compression algorithm, providing compression speed at 400 MB/s per_ \rightarrow core. It features an extremely fast decoder, with speed in multiple GB/s per core. magma: magma/2.5.4, magma/2.6.1-CUDA-11.3.1 The MAGMA project aims to develop a dense linear algebra library similar to LAPACK_ →but for heterogeneous/hybrid architectures, starting with current Multicore+GPU_ \rightarrow systems. makeinfo: makeinfo/6.7-minimal makeinfo is part of the Texinfo project, the official documentation format of the \rightarrow GNU project. This is a minimal build with very basic functionality. Should only be →used for build dependencies. matplotlib: matplotlib/3.4.2 matplotlib is a python 2D plotting library which produces publication quality. → figures in a variety of hardcopy formats and interactive environments across platforms. \rightarrow matplotlib can be used in python scripts, the python and ipython shell, web application servers, \rightarrow and six graphical user interface toolkits. ncurses: ncurses/6.1, ncurses/6.2 The Ncurses (new curses) library is a free software emulation of curses in System V_ \rightarrow Release 4.0, and more. It uses Terminfo format, supports pads and color and multiple →highlights and forms characters and function-key mapping, and has all the other SYSV-curses_ \rightarrow enhancements over BSD Curses.

ncview: ncview/2.1.8 Ncview is a visual browser for netCDF format files. Typically you would use ncview_ →to get a quick and easy, push-button look at your netCDF files. You can view simple. \rightarrow movies of the data, view along various dimensions, take a look at the actual data values, change_ \hookrightarrow color maps, invert the data, etc. netCDF: netCDF/4.7.4, netCDF/4.8.0 NetCDF (network Common Data Form) is a set of software libraries and machine---independent data formats that support the creation, access, and sharing of array-→ oriented scientific data. netCDF-C++4: netCDF-C++4/4.3.1 NetCDF (network Common Data Form) is a set of software libraries and machine---independent data formats that support the creation, access, and sharing of array-→ oriented scientific data. netCDF-Fortran: netCDF-Fortran/4.5.2, netCDF-Fortran/4.5.3 NetCDF (network Common Data Form) is a set of software libraries and machine-→oriented scientific data. networkx: networkx/2.5.1 NetworkX is a Python package for the creation, manipulation, and study of the →structure, dynamics, and functions of complex networks. nsync: nsync/1.24.0 nsync is a C library that exports various synchronization primitives, such as mutexes numactl: numactl/2.0.13, numactl/2.0.14 The numactl program allows you to run your application program on specific cpu's and. →memory nodes. It does this by supplying a NUMA memory policy to the operating system. \rightarrow before running your program. The libnuma library provides convenient ways for you to add. →NUMA memory policies into your own program. pkg-config: pkg-config/0.29.2 pkg-config is a helper tool used when compiling applications and libraries. It helps \rightarrow you insert the correct compiler options on the command line so an application can use →gcc -o test test.c `pkg-config --libs --cflags glib-2.0` for instance, rather than hard- \hookrightarrow coding values on where to find glib (or other libraries). pkgconfig: pkgconfig/1.5.4-python pkgconfig is a Python module to interface with the pkg-config command line tool protobuf: protobuf/3.14.0, protobuf/3.17.3 Google Protocol Buffers

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protobuf-python: protobuf-python/3.14.0, protobuf-python/3.17.3
   Python Protocol Buffers runtime library.
 pybind11: pybind11/2.6.0, pybind11/2.6.2
   pybind11 is a lightweight header-only library that exposes C++ types in Python and
\rightarrow vice versa, mainly to create Python bindings of existing C++ code.
 rootless-docker: rootless-docker
 scikit-build: scikit-build/0.11.1
   Scikit-Build, or skbuild, is an improved build system generator for CPython C/C++/
→Fortran/Cython extensions.
 scikit-learn: scikit-learn/0.24.2
   Scikit-learn integrates machine learning algorithms in the tightly-knit scientific
-Python world, building upon numpy, scipy, and matplotlib. As a machine-learning module,
\rightarrow it
   provides versatile tools for data mining and analysis in any field of science and
\rightarrowengineering. It strives to be simple and efficient, accessible to everybody, and
\rightarrow reusable in
   various contexts.
 snappy: snappy/1.1.8
   Snappy is a compression/decompression library. It does not aim for maximum.
→compression, or compatibility with any other compression library; instead, it aims for
\rightarrow very high speeds
   and reasonable compression.
 tensorboard: tensorboard/2.8.0
   TensorBoard is a suite of web applications for inspecting and understanding your
→ TensorFlow runs and graphs.
 typing-extensions: typing-extensions/3.7.4.3, typing-extensions/3.10.0.0
   Typing Extensions - Backported and Experimental Type Hints for Python
 util-linux: util-linux/2.35, util-linux/2.36
   Set of Linux utilities
 x264: x264/20201026, x264/20210414
   x264 is a free software library and application for encoding video streams into the
→H.264/MPEG-4 AVC compression format, and is released under the terms of the GNU GPL.
 x265: x265/3.3, x265/3.5
   x265 is a free software library and application for encoding video streams into the.
\rightarrowH.265 AVC compression format, and is released under the terms of the GNU GPL.
 xorg-macros: xorg-macros/1.19.2, xorg-macros/1.19.3
   X.org macros utilities.
 zlib: zlib/1.2.11
   zlib is designed to be a free, general-purpose, legally unencumbered -- that is, not.
```

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\rightarrow covered by any patents -- lossless data-compression library for use on virtually any
\hookrightarrow computer
   hardware and operating system.
 zstd: zstd/1.4.5, zstd/1.4.9
   Zstandard is a real-time compression algorithm, providing high compression ratios.
\rightarrow It offers a very wide range of compression/speed trade-off, while being backed by a
→very fast
   decoder. It also offers a special mode for small data, called dictionary compression,
\rightarrow and can create dictionaries from any sample set.
        _____
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To learn more about a package execute:
  $ module spider Foo
where "Foo" is the name of a module.
To find detailed information about a particular package you
must specify the version if there is more than one version:
  $ module spider Foo/11.1
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_____
```